

**Course Title**

# An Introduction to Robotics

Two Day Weekend Curriculum - Total 8 Hours

**Synopsis**

Robotics enable children to "do" mathematics and science rather than study them. Using motivational effects of robotics, this introductory module is designed to excite students about learning math, science and engineering concepts. Participants are introduced academic concepts in a context that makes sense to them. As they design, build and program an autonomous robot, participants are exposed to advance math, science and engineering concepts in a 'hands-on mind-on' inquiry-based format.

Children will be taught about the continuing evolution of Robotics in the real world and how it impacts their daily lives. Participants will use Lego Mindstorm™ to design and build a simple robot and control their robots using the ROBOLAB™ software. Subsequently, they will add sensors to the robots they have built and learn how to program it to sense and react with its surroundings.

Our teacher becomes the facilitator; introducing background information thus preparing students for investigations. Lessons are designed to introduce/reinforce math, science, and technology concepts. As lessons evolve, children begin to recognize the relevance of the academic concepts used as they are delivered accordingly.

**Students**

This course is designed primarily for children between 10 and 17 years old. Younger children who are computer literate may be included.

| Course Content   | Duration (HH:MM) | Course Content  | Duration (HH:MM) |
|--|------------------|---|------------------|
| <b>Day 1 - The Basics</b>  | <b>4:00</b>      | <b>Day 2 - Design Challenges</b>  | <b>4:00</b>      |
| <b>Introduction</b><br>Brief Introduction to Robotics  | <b>0:10</b>      | <b>Review of Day 1's Lessons</b>  | <b>0:15</b>      |
| <b>Hardware</b><br>Lego Components<br>Standard Parts<br>Specialty Parts<br>The RCX<br>Building your first robot - The RoboTank   | <b>0:20</b>      | <b>Design Ideas</b><br>Lego Constructopedia<br>Mechanical design ideas<br>Programming samples | <b>0:30</b>      |
| <b>Software</b><br>RoboLab Programming Environment and Tutorial  | <b>1:20</b>      | <b>Challenge #1 - Easy</b><br>Introduction<br>Team @Work<br>Presentation                      | <b>1:00</b>      |
| <b>Investigation # 1</b><br>Motor 1 - Forward<br>Motor 2 - Forward and Backward<br>Motor 3 - Point Turn<br>Motor 4 - Modifier<br>Motor 5 - Loops                                   |                  | <b>Challenge #2 - Moderate</b><br>Introduction<br>Team @Work<br>Presentation                  | <b>2:00</b>      |
| <b>Motor &amp; Gears</b><br>Introduction to Motor, Gears and Gear Ratio  | <b>0:50</b>      | <b>Closing Review</b>   | <b>0:15</b>      |
| <b>Investigation # 2</b><br>Mechanics 1 - Gear and Speed   |                  |   |                  |
| <b>Sensors</b><br>Introduction to Lego Touch and Light Sensors<br>Building Touch Sensors   | <b>1:20</b>      |   |                  |
| <b>Investigation # 3</b><br>Touch Sensor 1 - Wait for Push<br>Touch Sensor 2 - Wait for Let Go / Conditional<br>Touch Sensor 3 - Bug Bot / Multi-tasking<br>Building Light Sensors |                  |   |                  |
| <b>Investigation # 4</b><br>Light Sensor 1 - Wait for Dark<br>Light Sensor 2 - Wait for Light<br>Light Sensor 3 - Line Tracker   |                  |   |                  |

